

## **REMARKS**

The specification of the subject U.S. patent application, as filed, as constituted by the verified translation of PCT/EP2004/050648, has been cancelled in favor of the concurrently submitted Substitute Specification. A suitable Abstract of the Disclosure has been added. These changes and corrections do not constitute any new matter.

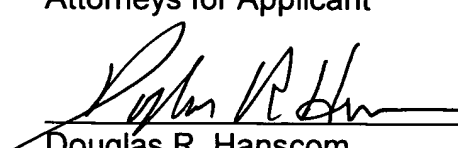
Original claims 1-30, and Article 34 claims 1-28 have been cancelled. New claims 31-58 have been added. New claims 31-58 are essentially the same, in scope, as the claims which are pending in the corresponding PCT application. They have been rewritten more in a form in accordance with U.S. practice and eliminating multiple dependencies

Entry of this Preliminary Amendment into the file of the subject U.S. patent application, prior to an examination of this application on the merits, and prior to the calculation of the filing fee, is respectfully requested.

Respectfully submitted,

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**MARKED-UP COPY OF SPECIFICATION**  
**SCHNEIDER, STARK W1.2219 PCT-US**

[Specification]

**PRINTING UNITS AND METHOD FOR MOVING A FRAME PART**

**CROSS-REFERENCE TO RELATED APPLICATIONS**

[001] This patent application is the U.S. National Phase, under 35 USC 371, of PCT/EP2004/050648, filed April 29, 2004; published as WO 2005/037552 A1 on April 28, 2005 and claiming priority to DE 103 47 573.7, filed October 14, 2003, the disclosures of which are expressly incorporated herein by reference.

**FIELD OF THE INVENTION**

[002] The present invention is directed[relates] to printing units and to a method for moving a frame element[, in accordance with the preamble of claim 1, 2, 25 or 30]. At least one cylinder or roller of the printing unit is mounted on a frame. The frame is movably supported by rollers which can be shifted between an extended position and a retracted position.

**BACKGROUND OF THE INVENTION**

[003] A printing unit is known from EP 0 749 369 B1, in which rollers are mounted in the movable frame element and rest on horizontal rails. These rollers[

[WO 2005/037552]

[PCT/EP2004/050648]

and] also support the stationary frame element. In [connection with ]a printing unit of dimensions suitable for newspaper printing, the load resting on each roller of the movable frame element can reach an amount[s] of several tons. Thus, extreme pressures occur at the contact faces between the rollers and [the ]rails on which they roll. While the rollers can be made of hardened steel, which can withstand being[ be] subjected to the occurring pressures, use of this hardened steel is difficult, in connection with the rails, because of their dimensions. However, [But] if the rails are made of[on] non-hardened steel the danger arises that the wheels may be[are] pressed into the rails and it becomes impossible to move the movable frame element evenly, or to put it into motion at all.

[004] USP 5,060,569 discloses a frame element which can be moved on rollers. The[, wherein the] rails are raised for movement and the frame element rests on another frame element during operations.

[005] DE 34 46 619 A1 describes a frame element which can be moved on rails.

[006] To assemble[For assembling] a printing press, it is set forth in[known from] the MAN Roland prospectus "5 that it is a very useful thing ..." to move printing units by means of adjustable rollers.

### **SUMMARY OF THE INVENTION**

[007] The object of the present invention is directed to providing[based on creating] printing units and to a method for moving a frame element.

[008] In accordance with the present invention, this object is attained by the provision of at least one cylinder or roller of a printing unit being seated in a movable frame element which is movable by the use of extendable and retractable rollers. When these rollers are extended, they support the movable frame element. When the rollers are retracted, the movable frame element is supported, at least in part, on a stationary support by a contact surface, which is not the rollers. The stationary support is constituted by the roller engaging rails and by an upright guide rail which is connected with the movable frame element[means of the characteristics of claims 1, 2, 25 or 30].

[009] Because[By means] of the retractability of the rollers, the possibility of

[WO 2005/037552]

[PCT/EP2004/050648]

displacing a weight resting on them at least partially to a contact surface different from the rollers is provided. The[created, and of relieving the] rollers are, in this way, relieved of the weight resting on them to the extent that the pressing of the rollers into a support need no longer be feared.

[010] Since such a contact surface can easily be made larger than the contact surface which exists between a roller and a support, it is possible to decrease weight related[occurring] pressure loads, even if the entire weight of the movable frame element is displaced to the contact surfaces which are different from the rollers. The[, and the] demands made on the load carrying capability of a support on which the movable frame element is supported can be reduced.

[011] The rails, on which the rollers rest in the extended state, are used as supports on which the contact surfaces, which are different from the rollers, are supported.

[012] The contact surfaces can be [simply ]constituted simply by the lower edges of lateral frame plates of the movable frame element.

[013] Preferably, each frame element has at least one rubber blanket cylinder

[WO 2005/037552]

[PCT/EP2004/050648]

as the cylinder delimiting the printing gap, a forme cylinder and an inking system, so that the two rubber blanket cylinders, forme cylinders, and the like[etc.] each constitute a printing unit in bridge construction suitable for recto- and verso-printing.

[014] The displaceability of the rollers between their[the] extended and the retracted positions is preferably achieved wherein[in that] each [of] rotatable shaft[s] of the associated roller[s] is pivotably maintained on the movable frame element. A[Preferably a] pneumatic or a hydraulic actuating member is preferably employed for driving [a pivot movement of] at least one of the rollers in a pivot movement around its eccentric axis.

[015] If [respectively] two rollers, which can respectively be pivoted around a common eccentric axis, are arranged on a common torsion-proof shaft, a single actuating member can be employed for accomplishing the pivoting of both of the rollers. Tilting[ and/or tilting] of the printing unit, during the retraction and extension of the rollers, can thus be avoided.

[016] In connection with a movable frame element with two lateral frame plates,

[WO 2005/037552]

[PCT/EP2004/050648]

the two rollers, which can be pivoted around a common eccentric axis, are [respectively] arranged in such a way that they each support different one of these frame plates.

[017] Several rollers, and in particular those rollers which are running on a common rail or which are supporting the same frame plate, can be pivotably coupled by the use[means] of a rod, which rod acts on shafts of the rollers via levers.

[018] To[In order to] fix the positions of the two frame elements in relation to each other in a working position, where they are not spaced apart, a protrusion is preferably formed on one of the frame elements. This protrusion[ and] is oriented in the movement direction of the movable frame element. A[, and a] cutout, which is shaped in a complementary manner to the protrusion, is formed on the other frame element. The protrusion and the cutout will[, which] come into positive engagement with each other when the frame elements are arranged without a space between each other.

[019] The protrusion or the cutout can automatically provide a centering effect

[WO 2005/037552]

[PCT/EP2004/050648]

when the frame elements are brought together. This is particularly effective if the protrusion is tapered towards its free end and/or the cutout tapers toward a bottom.

[020] The protrusion is preferably shaped as a vertically oriented rib. The [ and the] cutout is preferably shaped as a vertically oriented groove in order to define the position of the two frame elements relative to each other only in a horizontal direction transversely to the movement direction, but not in the vertical direction.

[021] For use in guiding the movement of the movable frame element, [preferably] at least one upright guide rail is preferably provided. This guide rail [ which] extends in the movement direction of the movable frame element, is fixedly connected with one of the frame elements and is enclosed on two sides by a track guidance device of the other frame element. This track guidance device is preferably comprised of [comprises] at least one pair of guide rollers, which roll off on the sides of the guide rail.

[022] For use in moving the movable frame element, a toothed rack, which is extending in the movement direction of the movable frame element, is suitably



[WO 2005/037552]

[PCT/EP2004/050648]

mounted on one of the frame elements. On[, and on] the other frame element, a self-locking drive mechanism is used to engage[ engaging] the toothed rack, which self-locking drive mechanism can be disengaged from the toothed rack in order not to block the movement of the movable frame element in case of an interference. The greatly geared-down[ down-gearing] drive mechanism is preferably accomplished[realized] with the aid of a worm gear. This worm gear drive[It] is preferably pivotably attached to the frame for disengagement from the toothed rack.

[023] To[In order to] lock stationary and movable frame elements of the printing group together in their work position, [preferably ]at least one hook is preferably provided on one of the frame elements, which at least one hook can be brought into engagement with the other frame element. This at least one hook[ and] can be charged with a pulling force that is acting in a[the] direction toward the one frame element. Preferably, the movable frame element is identical to the previously[above] mentioned movable frame element, in addition to the frame element fixed in place on the frame, the stationary frame element can also include

the support.

[024] The hook preferably engages a roller of the other frame element. The hook's[, so that its] movement into the engagement position and out of the engagement position is not hampered by too strong frictional forces. A pneumatic or a hydraulic actuating member is preferably used for driving the hook in a pivot movement [of the hook ]into the engagement position or out of it. The supply of the actuating member with pressure fluid is simplified if the frame element<sub>1</sub> to which the hook and the actuating member are attached<sub>1</sub> is the stationary frame element.

[025] At least one hook should exert a pulling force<sub>1</sub> with a downward directed component<sub>1</sub> on the movable frame element in order to fix the latter in place also in the vertical direction.

### **BRIEF DESCRIPTION OF THE DRAWINGS**

[026] Preferred[Exemplary] embodiments of the present invention are represented in the drawings and will be described in greater detail in what follows.

[027] Shown are in:

Fig. 1, a schematic side elevation view[representation] of a printing group with a movable frame element which is spaced apart from a[the] stationary frame element, in

Fig. 2, the printing group depicted in Fig. 1, with the movable frame element in a position wherein it is not spaced apart from the stationary frame element, and with rollers extended, in

Fig. 3, the printing group in Fig. 1 with the[retracted] rollers retracted in a work position, in

Fig. 4, a schematic depiction of[schematically] the suspension of the rollers from a lateral frame plate of the movable frame element, in an[the] extended position, in

Fig. 5, a schematic depiction of the movable frame element, with the rollers in the retracted position, in

Fig. 6, a perspective [plan ]view, from above, of a running gear of the movable frame element, as well as of rails of the stationary frame element on which the running gear moves, in

Fig. 7, a schematic cross-sectional view through a wheel box of the running gear in accordance with Fig. 6, in

Fig. 8, a drive mechanism for use in accomplishing[driving] the movement of the movable frame element along the rails, in

Fig. 9, a schematic cross-sectional view through the drive mechanism depicted in Fig. 8, in

Fig. 10, a schematic plan view of a locking mechanism for locking the frame elements together, in

Fig. 11, a partial cross-sectional[partially cut] view, from above of[on] the locking mechanism shown in Fig. 10[9], in

Fig. 12, a schematic plan view of a locking mechanism for use in locking the movable frame element on the support, in

Fig. 13, a schematic representation of a printing group with two movable frame elements and with one frame element fixed in place, and in

Fig. 14, a schematic representation of a locked position of a printing unit in accordance with Fig. 13.

**DESCRIPTION OF THE PREFERRED EMBODIMENTS**

[028] Figs. 1 to 3 illustrate the basic operative principle of the present invention.

A[Shown is a] printing unit is shown and which is provided with four printing groups, which printing groups are arranged one above the other and which each have pairs of cylinders 01, such as, for example, rubber blanket cylinders 01 or rollers. In a manner which is known per se, a plate cylinder, an inking system and a dampening system are assigned to each rubber blanket cylinder 01. These cylinders and systems[ and] are maintained between respective lateral frame plates 02, 03. The interior structure of the printing groups will not be described in detail here, since such a description[it] is not required for an understanding of the present invention. A[, a] description of this type of interior structure is provided in EP 0 749 369 B1, to which reference is hereby made.

[029] The two spaced lateral frame plates 02, together with the cylinders 01[,]  
and the inking and dampening systems which they support, form a fixed frame element 13. This frame element 13[, which] is fixed on a press main[the] frame and is solidly mounted between [the ]upper and lower supports 04, 06 of that main

press frame. The two spaced lateral frame plates 03, together with the cylinders 01, inking and dampening systems which they support, form a movable frame element 15. These two spaced lateral frame plates 03, they] are fixedly mounted between the upper and lower supports 04, 06, which are respectively constructed with[on] parallel rails 05 which are transversely connected with each other, as may be seen in[(see] Figs. 6 and 12[)]. The two spaced lateral frame plates 03 are provided with rollers 07 on their lower edge, which rollers 07 can be displaced between an extended position and a retracted position. The two frame plates 03,.] together with the components maintained between them,.[ they] form a movable frame element 15. Fig. 1 shows the rollers 07 in their extended position, in which extended position, rollers 07[they] keep the lateral frame plates 03 spaced apart from the rails 05 of the lower support 06. These rails 05 are, at the same time, used as a track, on which the rollers 07 roll off.

[030] Fig. 1 shows the movable frame element 15 in an open or separated[a] position in which[wherein] it is spaced apart from the lateral frame plates 02 and in which spaced apart position an operator 08 can enter a[the] space between the

pairs of rubber blanket cylinders 01 and can perform maintenance work, such as a change of rubber blankets. Following the completion of the maintenance work, the movable frame element 15 is displaced toward the left in Fig. 1 until it reaches the closed or contiguous position represented in Fig. 2, in which closed position the stationary lateral frame plates 02 and the movable lateral frame plates 03 touch each other at respective edges 09, 11 that are facing each other. In this closed position, [still ]with [extended ]rollers 07 still extended, the rubber blanket cylinders 01 of the movable lateral frame element 15 lie slightly higher than those of the stationary one. By bringing the rollers 07 into their retracted position, in which they no longer protrude past the lower edge of the lateral frame plates 03, the movable frame element 15 is lowered a further distance, as represented in Fig. 3, so that the lower edges of the lateral frame plates 03 now lie on the rails 05 of the support 06. In[ and in] this closed, engaged position, [way] the pairs of rubber blanket cylinders 01 respectively arrive at the same height and form a printing gap, in which a web 12 of material, such as, for example, a paper web 12, which is conducted between the blanket cylinders 01 [them], can be imprinted.

[031] While in the positions shown schematically in Figs. 1 and 2, the rollers 07 support the entire weight of the movable frame element 15, including that of with the lateral frame plates 03 and the cylinders 01 of the several printing groups which are held between them, and transfer that weight[it] to a small surface of the lower support 06. In[, in] the position depicted schematically in Fig. 3, in which the entire lower edge of the lateral frame plates 03 rests on the lower support 05, the weight is distributed over a substantially greater area than the area[ one in] which receives that weight when the frame element 15 is [only ]supported only by the rollers 07. The rollers 07 thus support the movable frame element 15 only when it is to be moved, and possibly if, as represented in Fig. 1, the movable frame element 15[it] is spaced apart from the stationary frame element 13 and the space between the frame elements 13, 15 is accessible. This spacing, and weight support by rollers 07 is occasioned[, i.e.] only during comparatively short periods of time. During a[the] printing operation, the lateral frame plates 03 rest with their lower edges on the lower support 06. Thus, there is no danger that the rollers 07 will press into the lower support 06, or that the rails 05 of the lower support 06 are



damaged in other ways, so that the mobility of the movable frame element 15 would be hindered by this type of damage.

[032] A preferred mechanism for retracting and for extending the rollers 07 is represented schematically in Figs. 4 and 5, wherein Fig. 4 shows the rollers 07 in the extended position, and [in ]Fig. 5 shows the rollers 07 in the retracted position. The rollers 07 have a rotatable shaft 14, which is hinged by the use[means] of a first, pivot lever arm 17 on a pivot shaft 16, which pivot shafting is stationary with[in] respect to the lateral frame plate 03. A second, actuating lever arm 18 is rigidly connected, at one end, with the first, pivot lever arm 17 of a[the] right roller 07. A[ and its] free end of actuating lever arm 18 engages a piston rod 19 of a pneumatic or a hydraulic actuating member 21, such as, for example, a hydraulic cylinder 21. One end of a rod 22, for example a synchronizing rod 22, is hinged to a free end of a third lever arm 23, which is rigidly connected with the first, pivot lever arm 17 of the left roller 07. A second[, and the other] end of synchronizing rod 22 is hinged to an intermediate point[spot] on the second, actuating lever arm 18. The distance of the intermediate point[spot] from the

adjoining eccentric shaft 16, such as, for example, the pivot shaft 16, corresponds to the length of the third, working lever arm 23, so that the second and third lever arms 18, 23, which are coupled to each other by [means of ]the synchronizing rod 22, always perform the same rotating movement. In the position depicted in Fig. 4, a first chamber 26 of the hydraulic cylinder 21, which is facing away from the piston rod 19, has been put under pressure, so that the piston rod 19 is extended out of actuating member 21 as far as a stop and this maintains the rollers 07 in the extended position. The piston rod 19 is slowly retracted, into member 21, by [means of ]the controlled release of pressure gas from the chamber 26. The [ and the] rollers 07 pivot in a counterclockwise direction around their pivot shafts 16 until the lower edge of the lateral frame plate 03 rests on the support 06. When[Then] the rollers 07 are in the retracted position, in which they rest loosely on the support 06, they can be lifted off the support 06 into the position represented in Fig. 5 by charging a second chamber 27 of the hydraulic cylinder 21, which second chamber 27 is facing the piston rod 19.

[033] Fig. 6 shows a detailed representation of a running gear of the movable

frame element 15, as well as of two rails 05 of the lower support 06 on which the running gear can be moved. The previously[already] described hydraulic cylinder 21, the piston rod 19 and the actuating lever arm 18 can be seen in Fig. 6[recognized]. The end of the hydraulic cylinder 21, which is facing away from the piston rod 19, is connected with a horizontal arm 28 that is extending from a flange 29, from whose side facing away from horizontal arm 28, [the viewer] four pins 31 project. These pins 31 are screws 31, which are used[provided] for securing[screwing] the flange 29 to one of the two lateral frame plates 03 of the movable frame element 15, [(which lateral frame plates 03 are not represented in Fig. 6)]. Corresponding pins 32, or screws 32, that are used for the same purpose, protrude past the lateral walls of two wheel boxes 33, 34. Each one of the wheel boxes 33, 34 contains one of the previously discussed[already mentioned] rollers 07.

[034] A schematic section through the wheel box 34 is represented in Fig. 7. The location[position] of the pivot shaft 16 is indicated by a cross. It is also the longitudinal axis of a shaft 36, for example a pivot shaft 36, which is extending

transversely through the wheel box 34, at which point the actuating lever arm 18, which is connected with the piston rod 19, acts on the pivot shaft 36 outside of the wheel box 34. The first, pivot lever arm 17 is realized by an eccentric sleeve 37, whose interior bore encloses the pivot shaft 36 and is fixed to pivot shaft 36 against relative rotation, and whose exterior circumference supports the[a] roller 07 by the use[means] of a bearing 38, such as, for example, a rolling bearing 38.

The center of the exterior circumference of the sleeve 37, which defines the axis of rotation of the roller 07, is identified by a cross at 39, as seen in Fig. 7. If the lever arm 18 is rotated in a clockwise direction, the center of sleeve 37 and of the rotatable shaft 36[39] moves along the arrow 41, so that [finally] a portion of the running face of the roller 07 emerges from the open underside of the wheel box 34.

[035] As is shown in Fig. 6, the pivot shaft 36 extends, starting at the wheel box 34, transversely underneath the movable frame element 15 and crosses through a second wheel box 42, on which a second roller 07 is mounted in the same way as in the first wheel box 34. The second roller is positioned on the second lateral

frame plate 03 in a manner the same as is used to secure the first roller 07 and the first wheel box 34 to the first lateral frame plate 03 of the movable frame element 15.

[036] The synchronizing rod 22 acts on the one hand via a working lever arm 43, and on the other hand via the lever arm 23, on the pivot shaft 36, as well as on a second shaft 44, for example a second pivot shaft 44, which is parallel with the first pivot shaft 36[it] and which passes through the wheel boxes[box] 46 and 33.

The movements of all of rollers 07 between[ into] the extended or retracted position are coupled to each other by the synchronizing rods 22 and by the continuous rigid pivot shafts 36, 44.

[037] A guide rail 47, which is provided[here] with an F-shaped cross section, is rigidly connected with the two wheel boxes 33, 34, as seen in Fig. 6. This guide rail 47, which can be displaced together with the movable frame element 15, has a vertically downward directed rib 48 which, in case of a displacement of the frame element 15, moves with contact between two pairs of guide rollers 49. These guide rollers 49[, which] are mounted on one of the support rails 05 and are

remote from a rolling surface of the support rail 05 over which the rollers 07 move.

The cooperation between the guide rail 47 and the guide rollers 49

enforces[forces] an exactly linear movement of the movable frame element 15

along the support rails 05, without the possibility of an offset of the movable frame

element 15 transversely to the longitudinal direction of the rails 05. Although they

are not specifically represented, a corresponding guide rail 47 and guide rollers 49

can also be mounted on the wheel boxes 42, 46, or on the lower support 06 of the

main press frame which, as depicted in Fig. 6, faces the viewer.

[038] The drive mechanism, which is represented in a perspective plan view in

Fig. 8, is mounted on the running gear, or on one of the lateral frame plates 03

mounted thereon, of the movable frame element 15. Two rigid arms 51 project

transversely, with[in] respect to the movement direction of the movable frame

element 15 away from the running gear, or away from one of the lateral frame

plates 03. Between them, these arms 51 support a drive unit 53, which is hingedly

suspended from a shaft 52 and which drive unit 53 has a motor 54, such as, for

example, an electric motor 54, which electric motor 54 drives an output[a] gear

wheel 56 via a self-locking reduction gear which is housed in the drive unit 53. In the [represented ]position of the drive unit 53, depicted in Fig. 8 the output gear wheel 56 meshes with a stationary toothed rack 57.

[039] Fig. 9 shows a cross-section through the drive mechanism depicted in Fig. 8. The[It can be seen that the] drive unit 53 is supported by a projection 58 of a pivot lever handle 59 which is hinged on one of the arms 51. The[, and the] gear wheel 56 is maintained in engagement with the toothed rack 57 by [means of ]this support of the drive unit 53. If the pivot lever handle 59 were lifted, the drive unit 53 could pivot in a clockwise direction around the shaft 52 and in this way could move the gear wheel 56 out of the toothed rack 57. This will[ and] cancel the non-positive connection between the electric motor 54 and the toothed rack 57.

[040] A drive gear wheel 61, which is directly driven by the electric motor 54 and which meshes with a larger driven gear wheel 62, is located inside the drive unit 53. Driven gear wheel 62[It] is mounted on a common shaft together with a worm 63, which, in turn, meshes with a worm wheel 64. This worm wheel or gear 64[, which] is mounted on a common shaft with the gear wheel 56. The worm 63 and

the worm wheel 64 cause self-locking of the gear, by means of which the output gear wheel 56 is arrested when the electric motor 54 is switched off.

[041] Fig. 10 shows a portion of one of the stationary lateral frame plates 02 and a portion of one of the movable lateral frame plates 03, whose vertical edges 09, 11 touch each other in the closed, engaged operating position of the printing unit. A, having a] mechanism for locking the lateral frame plates 02, 03 with each other in the operating position is shown in Fig. 10. This locking mechanism includes a pivotable hook 66, which is hinged to a forked bearing block 67, as is shown in section in Fig. 10. Two bores 68 are used for screwing or otherwise attaching the bearing block 67 on the lateral frame plate 02. These, these] bores 68 permit limited horizontal play of the bearing block 67. In spite of measurement tolerances of the hook 66 and of the lateral frame plates 02, 03, this limited horizontal play allows the exact placement of the bearing block 67 in such a way that an interior flank 69 of the hook 66 extends around a locking protrusion 71 on the movable lateral plate 03 with exact contact. The radius of the interior flank 69 of the hook 66, in relation to the pivot shaft of the hook 66 on the bearing block 67,



is slightly decreased in a counterclockwise direction. The[, so that the] interior flank 69 of hook 66 is thus capable of extending behind the locking protrusion 71, even if the edges 09, 11 of the lateral frame plates 02, 03 do not directly touch each other. The[, and of pulling the] two lateral frame plates 02, 03 are then pulled against each other by pivoting the hook 66 in a clockwise direction until edges 09, 11[they] touch each other in the contact position shown in Fig. 10. The pivot movement of the hook 66 is driven by an actuating member 72, such as, for example, a pneumatic cylinder 72.

[042] The locking protrusion 71 is constituted by a central pin 73, which is fixedly connected with the lateral frame plate 03, and by a roller 74 that is seated in a roller bearing and which is surrounding the pin 73. This roller 74 can turn or rotate[along] when the hook 66 is pressed onto[on] the locking protrusion 71, so that, in spite of the considerable tractive forces which the hook 66 can exert on the locking protrusion 71 in the course of pivoting of the hook 66, the movement of the hook 66 is not blocked by too much friction.

[043] To prevent[For preventing] the bearing block 67 from slipping on the

lateral frame plate 02 about its connection through bores 68, so that sufficient tractive force would[can] no longer be able to be exerted on the locking protrusion 71, the bearing block 67 is additionally secured by two securing screws 76. These securing screws 76[, which] are screwed into the bearing block 67 from the direction of a retaining block 77 which is rigidly fastened to the plate 02. Fig. 10 shows these two securing screws 76 tightened until they make contact, so that the bearing block 67 touches the retaining block 77. If the securing screws 76 are loosened a little, it is possible to place the bearing block 76 a little closer to the edge 09 and to fix it in place on the lateral frame plate 02 with the aid of screws entering into the bores 68.

[044] Fig. 11 shows the locking mechanism of Fig. 10 partially in a view from above and partially in cross-section. The pneumatic cylinder 72 and the hook 66, which it hingedly engages, can be seen. Two depressions have been formed at the touching edges 09, 11 of the lateral frame plates 02, 03. An[, wherein an] insertion body 78, with a vertical cutout 79, such as, for example, a groove 79 of a trapezoidal cross section, is screwed into the depression of the lateral frame plate

02. An[, and an] insertion body 81 with a protrusion 82, such as, for example, a rib 82 which positively engages the groove 79, is housed in the recess of the lateral frame plate 03. The insertion body 81 is simultaneously used as a support for the pin 73 and for the roller 74 of the locking protrusion 71.

[045] The rib 82 and the cooperatively shaped groove 79 provide an exactly flush alignment of the lateral frame plates 02, 03, with[ in] respect to each other, transversely to the movement direction of the movable frame element 15 when they touch each other in the closed, engaged operating position of the printing unit. In order to avoid redundancy, insertion bodies 81 with the groove 79 and rib 82 are only provided at one of the two lateral frame plates 02, 03 of the stationary frame element 14 or the movable frame element[s] 15, respectively. The[ the] insertion bodies which are attached to the [respectively] other respective lateral frame plate 02, 03 are flat on their facing sides. The rib 82 and the groove 79 permit a vertical movement of the lateral frame plates 02, 03 against each other in the course of the transition of the rollers 07 between[ from] the retracted and the extended positions.

[046] Fig. 12 shows two hooks 83, which are respectively provided in pairs on the two lower supports 06 of the main press frame. A first hook 83, which is formed with a ramp-shaped upper side, is pivotable around a shaft 84 which is situated adjacent an edge 09 of [ at] the lateral frame plate 02 and which first hook 83 has a notch 86 on its upper side. This notch 86 [ which], in the locked state of the first hook 83, receives a locking protrusion 87 carried on[of] the lateral frame plate 03. The structure of the locking protrusion 87 is the same as that of the locking protrusion 71 discussed above. An actuating member 88, such as, for example, a pneumatic cylinder 88, which is mounted, substantially horizontally oriented, on the lower support 06 of the main press frame, is used for locking and unlocking the hook 83. The piston rod of the pneumatic cylinder 88 is hinged to a first rod 89, which acts on the hook 83, and to a second rod 91, whose second end is, in turn, hinged to the support 06 and which second rod 91 forms an angle with the first rod 89. When the piston rod is retracted from the [represented] extended position represented in Fig. 12, the angle between the first and second rods 89, 91 is reduced. The result is that[,] the point of engagement of the rod 89 at the hook

83 is lowered, and the locking protrusion 87 is released. The[, so that the] movable frame member 15 can now be shifted.

[047] In a manner which is the[The] same as discussed in connection with the pneumatic cylinder 88, a second actuating member 92, such as, for example, a pneumatic cylinder 92[k], is substantially horizontally oriented on the support 06. Pneumatic cylinder 92[ and] has a piston rod which acts via two rods 93, 94, which are angled in relation to each other in a manner similarly to the rods 89, 91, on the [one side on the ]support 06 and on [the other side on ]a second hook 96. Like the first pivotable hook 66, this second pivotable hook 96 has an interior flank 97 which flank 97, in the course of extending the second hook 96, slides along a locking protrusion 98 of the lateral frame plate 03 and, in the process, exerts a tractive force on the locking protrusion 98, which tractive force is directed downward and in the direction toward the lateral frame plate 02. This tractive force[, which] becomes larger the closer the hook 96 is to its contact position represented in Fig. 12. The[Thus, the] hook 96 thus exerts a double locking function. For[, for] one, it keeps the lateral frame plate 03 pressed against the

lateral frame plate 02. It[, and it] also maintains the frame plate 03[it] fixed on the support 06.

[048] The three pivotable hooks 66, 83, 96 can each be actuated by the use[means] of a toggle lever, for example.

[049] In another preferred[exemplary] embodiment of the present invention, as seen in [(Fig. 13 and in Fig. 14)], the printing unit has three frame elements 104, 106, 107, each consisting of two lateral elements 102, [102, ]103, which are fixedly mounted between upper and lower supports 04, 06, of the main press frame.

Forme[ wherein forme] cylinders and transfer cylinders are arranged in the center frame element 106. Inking[, inking] systems, which are assigned to the forme cylinders, are arranged in the two outer frame elements 104 and 107.

[050] As represented in Fig. 13, the two outer frame elements 104 and 107 can be moved into a maintenance or set-up position, so that an accessible space between them and the fixed, center frame element 106 is provided[created].

[051] The combined, closed, operating state of these three frame elements 104, 106, 107 as represented in Fig. 14 is the production position, i.e. the position in

which the printing unit prints. In the course of coming into this production position, the three frame elements 104, 106, 107 are connected with each other by the use[means] of a locking device 108.

[052] In the depicted preferred embodiment[present example], the center frame element 106 has at least two pairs of cylinders arranged as a bridge printing group, but preferably has four bridge printing groups which are arranged to work together vertically.

[053] The forme cylinders of the several disclosed preferred[exemplary] embodiments preferably have at least two printing plates in the axial direction, and preferably have four printing plates.

[054] While preferred embodiments of printing units, and of a method for moving a frame part, in accordance with the present invention, have been set forth fully and completely hereinabove, it will be apparent to one of skill in the art that various changes in, for example, the drives for the various printing cylinders, the type of web being printed, and the like could be made without departing from the true spirit and scope of the present invention which is accordingly to be limited only by

[WO 2005/037552]

[PCT/EP2004/050648]

the appended claims.

WHAT IS CLAIMED IS:



[List of Reference Numerals]

01	Rubber blanket cylinder
02	Lateral frame plates
03	Lateral frame plates
04	Support, upper
05	Rail
06	Support, lower
07	Roller
08	Operator
09	Edge (02)
10	-
11	Edge (03)
12	Web of material, paper web
13	Frame element
14	Rotatable shaft
15	Frame element
16	Eccentric shaft, pivot shaft
17	Lever arm
18	Lever arm
19	Piston rod
20	-
21	Actuating member, hydraulic cylinder
22	Rod, synchronizing rod
23	Lever arm
24	Cylinder chamber
25	-
26	Chamber
27	Chamber
28	Arm]

- [29 Flange
- 30 -
- 31 Pin, screws
- 32 Pin, screws
- 33 Wheel box
- 34 Wheel box
- 35 -
- 36 Shaft, pivot shaft
- 37 Sleeve, eccentric
- 38 Rolling bearing
- 39 Rotatable shaft
- 40 -
- 41 Arrow
- 42 Wheel box
- 43 Lever arm
- 44 Shaft, pivot shaft
- 45 -
- 46 Wheel box
- 47 Guide rail
- 48 Rib
- 49 Guide roller
- 50 -
- 51 Arm
- 52 Shaft
- 53 Drive unit
- 54 Motor, electric motor
- 55 -
- 56 Gear wheel
- 57 Toothed rack
- 58 Protrusion
- 59 Pivot lever
- 60 -]

- [61 Gear wheel
- 62 Gear wheel
- 63 Worm
- 64 Worm wheel
- 65 -
- 66 Hook
- 67 Bearing block
- 68 Bore
- 69 Interior flange
- 70 -
- 71 Locking protrusion
- 72 Actuating member, pneumatic cylinder
- 73 Pin
- 74 Roller
- 75 -
- 76 Screw
- 77 Retaining block
- 78 Insertion body
- 79 Cutout, groove
- 80 -
- 81 Insertion body
- 82 Protrusion, rib
- 83 Hook
- 84 Shaft
- 85 -
- 86 Notch
- 87 Locking protrusion
- 88 Actuating member, pneumatic cylinder
- 89 Rod
- 90 -
- 91 Rod
- 92 Actuating member, pneumatic cylinder]

[WO 2005/037552]

[PCT/EP2004/050648]

- [93 Rod
- 94 Rod
- 95 -
- 96 Hook
- 97 Interior surface
- 98 Locking protrusion
- 99 -
- 100 -
- 101 Lateral frame plates
- 102 Lateral frame plates
- 103 Lateral frame plates
- 104 Frame element, outer
- 105 -
- 106 Frame element, center
- 107 Frame element, inner
- 108 Locking mechanism]